Contents

Preface xiii

1 Power system stability overview 1
1.1 General 1
1.2 Understanding power system stability 1
1.3 Classification of power system stability 3
1.3.1 Small signal stability 3
1.3.2 Transient stability 6
1.4 Need for modelling 8
1.5 Stability margin increase 9
References 10

Part I Modelling 11

2 Modelling of the synchronous machine 13
2.1 Introduction 13
2.2 Synchronous machine equations 14
2.2.1 Flux linkage equations 14
2.2.2 Voltage equations 15
2.2.3 Torque equation 16
2.3 Park's transformation 17
2.4 Transformation of synchronous machine equations 18
2.4.1 Transformation of flux linkage equations 18
2.4.2 Transformation of stator voltage equations 19
2.4.3 Transformation of the torque equation 25
2.5 Machine parameters in per unit values 26
2.5.1 Torque and power equations 30
2.6 Synchronous machine equivalent circuits 32
2.7 Flux linkage state space model 34
2.7.1 Modelling without saturation 34
2.7.2 Modelling with saturation 40
2.8 The current state space model 42
References 44

3 Synchronous machine connected to a power system 47
3.1 Synchronous machine connected to an infinite bus 47
3.1.1 Flux linkage state space model 49
3.1.2 Current state space model 55

3.2 Synchronous machine connected to an integrated power system 57
3.3 Synchronous machine parameters in different operating modes 58
3.4 Synchronous machine-simplified models 62
3.4.1 The classical model 62
3.4.2 The E'_q model 64
3.5 Excitation system 67
3.5.1 Excitation system modelling 68
3.6 Modelling of prime mover control system 74
3.6.1 Hydraulic turbines 75
3.6.2 Steam turbines 77
References 79

4 Modelling of transformers, transmission lines and loads 81
4.1 Transformers 81
4.1.1 Modelling of two-winding transformers 81
4.1.2 Modelling of phase-shifting transformers 91
4.2 Transmission lines 93
4.2.1 Voltage and current relationship of a line 94
4.2.2 Modelling of transmission lines 95
4.3 Loads 97
4.3.1 Static load models 99
4.3.2 Dynamic load models 101
4.4 Remarks on load modelling for stability and power flow studies 103
References 104

Part II Power flow 107

5 Power flow analysis 109
5.1 General concepts 109
5.2 Newton–Raphson method 111
5.2.1 Power flow solution with polar coordinate system 113
5.2.2 Power flow solution with rectangular coordinate system 114
5.3 Gauss−Seidel method 121
5.4 Decoupling method 123
5.4.1 Fast-decoupled method 125
References 129

6 Optimal power flow 131
6.1 Problem formulation 131
6.2 Problem solution 132
6.3 OPF with dynamic security constraint 137
References 142

Part III Stability analysis **145**

7 Small signal stability **147**
7.1 Basic concepts 147
7.1.1 Equilibrium points 149
7.1.2 Stability of equilibrium point 150
7.1.3 Phasor diagrams of synchronous machines 152
7.2 Small signal stability 154
7.2.1 Forced state variable equation 162
7.3 Linearised current state space model of a synchronous generator 164
7.4 Linearised flux linkage state space model of a synchronous generator 172
7.5 Small signal stability of multi-machine systems 177
References 183

8 Transient stability **185**
8.1 Synchronous machine model 186
8.2 Numerical integration techniques 192
8.3 Transient stability assessment of a simple power system 193
8.4 Transient stability analysis of a multi-machine power system 201
References 218

9 Transient energy function methods **221**
9.1 Definitions of stability concepts 221
9.1.1 Positive definite function 222
9.1.2 Negative definite function 222
9.1.3 Lemma 222
9.1.4 Stability regions 223
9.1.5 Lyapunov function theorem 223
9.2 Stability of single-machine infinite-bus system 225
9.3 Stability of multi-machine power system 234
9.3.1 Energy balance approach 235
9.3.2 TEF method 241
References 250

Part IV Stability enhancement and control **251**

10 Artificial intelligence techniques **253**
10.1 Artificial neural networks 253
10.2 Neural network topologies 255
10.2.1 Single-layer feed-forward architecture 255
10.2.2 Multi-layer feed-forward architecture 255
10.2.3 Recurrent networks 256
10.2.4 Back-propagation learning algorithm 256
10.3 Fuzzy logic systems 259

10.3.1 Fuzzy set theory 260
10.3.2 Linguistic variables 261
10.3.3 Fuzzy IF–THEN rules 261
10.3.4 Structure of an FL system 261
10.4 Neuro-fuzzy systems 263
10.4.1 Adaptive neuro-fuzzy inference system 263
10.4.2 Structure of the NFC 265
10.4.3 Online adaptation technique 267
10.5 Adaptive simplified NFC 269
10.5.1 Simplification of the rule-base structure 269
10.6 Control system design of the proposed ASNFC 272
References 274

11 Power system stabiliser 277
11.1 Conventional PSS 278
11.1.1 Configuration of common PSS 278
11.1.2 PSS input signals 279
11.1.3 Characteristics of common PSS 280
11.2 Adaptive control-based PSS 281
11.2.1 Direct adaptive control 282
11.2.2 Indirect adaptive control 283
11.2.3 Indirect adaptive control strategies 286
11.3 PS control-based APSS 287
11.3.1 Self-adjusting PS control strategy 287
11.3.2 Performance studies with pole-shifting control PSS 290
11.4 AI-based APSS 291
11.4.1 APSS with NN predictor and NN controller 292
11.4.2 Adaptive network-based FLC 293
11.5 Amalgamated analytical and AI-based PSS 297
11.5.1 APSS with neuro identifier and PS control 297
11.5.2 APSS with fuzzy logic identifier and PS controller 299
11.5.3 APSS with RLS identifier and fuzzy logic control 301
11.6 APSS based on recurrent adaptive control 301
11.7 Concluding Remarks 307
References 307

12 Series compensation 311
12.1 Definitions of transmission line parameters 311
12.2 Compensation of lossless transmission line 313
12.2.1 Determination of amount of series compensation 313
12.2.2 Transient stability improvement for lossless compensated line 316
12.3 Long transmission lines 319
12.3.1 Series compensation for long transmission lines 321
12.4 Enhancement of multi-machine power system transient stability 329

12.5 Investigation of transmission power transfer capacity 333
12.6 Improvement of small signal stability 335
12.7 Sub-synchronous resonance 340
12.7.1 The mechanical system 341
12.7.2 The electrical network 343
References 348

13 Shunt compensation 351
13.1 Shunt compensation of lossless transmission lines 351
13.1.1 Shunt-compensated line parameters 351
13.1.2 Transient stability enhancement for shunt-compensated lossless lines 353
13.2 Long transmission lines 357
13.3 Static var compensators 360
13.3.1 Characteristics of FC-TCR compensators 362
13.3.2 Modelling of FC-TCR compensators 362
13.4 Static synchronous compensator (STATCOM) 369
13.5 Application of ASNFC to shunt-compensated power systems 374
13.5.1 Simulation studies 375
13.5.2 Three-phase to ground short circuit test 376
References 377

14 Compensation devices 379
14.1 Introduction 379
14.2 Flexible AC transmission system 380
14.2.1 Thyristor-controlled series capacitor 380
14.2.2 Static synchronous series compensator 382
14.2.3 Static var compensator 384
14.2.4 Static synchronous compensator 387
14.2.5 Phase-shifting transformer 389
14.2.6 Unified power flow controller 389
References 392

15 Recent technologies 395
15.1 Energy storage systems 395
15.1.1 Chemical energy storage systems (batteries) 397
15.1.2 Flywheel energy storage 397
15.1.3 Compressed air energy storage 397
15.1.4 Pumped hydroelectric energy storage 398
15.1.5 Super capacitors 400
15.1.6 Superconducting energy storage 400
15.2 Superconductivity applications 409
15.2.1 Superconducting synchronous generators 409
15.2.2 Superconducting transmission cables 411
15.2.3 Superconducting transformers 411
15.2.4 Superconducting fault current limiters 412

15.2.5 SMES applications 416
15.2.6 Features of storage systems 418
15.3 Phasor measurement units 420
15.3.1 Structure of WAMS 420
15.3.2 Benefits of WAMS 421
15.3.3 Case studies 422
References 423

Appendix I Calculation of synchronous machine parameters in per unit/normalised form 427
Appendix II Nine-bus test system 437
Appendix III Numerical integration techniques 439
Appendix IV 15-bus, 4-generator system data 445
Index 449