
Contents

Preface	xvii
Part I Converters	1
1 Semiconductor power devices	3
1.1 Introduction	3
1.2 High-voltage SiC power devices	4
1.2.1 Characterization of 15 kV SiC N-IGBTs	4
1.2.2 Characterization of 10 kV SiC MOSFETs	9
1.3 Low-voltage SiC devices and its characteristics	11
1.3.1 Low-voltage gate drive design	11
1.3.2 Common-mode current minimization	12
1.4 Characterization of 1,200 V, 100 A SiC MOSFET	12
1.4.1 1,200 V, 100 A SiC MOSFET device characterization without complementary device of the half-bridge module	12
1.4.2 1,200 V, 100 A SiC MOSFET device characterization with complementary device of the half-bridge module	12
1.4.3 Hard-switching characterization of 1,700 V SiC MOSFET [11]	14
1.4.4 Performance comparison of MOSFET and IGBT	16
1.4.5 Gate drive design and characterization of 1,200 V/45 A infineon SiC JFET module [12]	23
1.4.6 SiC super-junction transistor characteristics	24
1.5 Zero voltage switching characterization of 12 kV SiC [14]	25
1.5.1 ZVS turn-on characteristics	26
1.5.2 ZVS turn-off characteristics	28
1.6 All SiC-based SST	34
1.7 Summary	39
Acknowledgements	41
References	41
2 Multilevel converters	43
2.1 Introduction	43
2.2 Basic concepts of multilevel converters	43
2.2.1 One-branch converter	44
2.2.2 Two branches, “H-bridge” converter	46
2.3 Electronic switches to implement the converters	47

2.3.1	NPC converter	47
2.3.2	FC converter	49
2.3.3	CHB converter	49
2.3.4	Combined topologies	53
2.4	Three-phase multilevel converters	54
2.4.1	Phase-to-phase and phase-to-neutral voltages	55
2.4.2	Space vector representation	56
2.5	Modulation strategies for multilevel converters	60
2.5.1	Voltage levels-based algorithms	61
2.5.2	Space vector-based algorithms	69
	References	72
	Further reading	73
3	Multi-input converters	75
3.1	Introduction	75
3.2	Realizing multi-input converter topologies	76
3.3	Multi-port converters	87
3.3.1	Synthesis of multi-port converters by extending multi-input topologies	87
3.3.2	Multi-port converters with dc link	89
3.3.3	Ac link multi-port power converters	92
3.4	Applications of multi-port power converters	97
3.4.1	Multi-port power converters for renewable energy systems	99
3.4.2	Application of multi-input converters in micro-grids	101
3.4.3	Multi-port converters for vehicular power systems	103
3.5	Summary	106
	References	106
4	Modular converters	111
4.1	Introduction	111
4.2	Modular converter topologies and description	115
4.2.1	MMCC arrangements and SM topologies	116
4.2.2	Basic modular multilevel cascade converters	121
4.3	Control strategies	125
4.3.1	Voltage-balancing control	125
4.3.2	Circulating current control	128
4.4	Modulation techniques	130
4.4.1	High switching frequency techniques	130
4.4.2	Low switching frequency techniques	132
4.5	Operational issues in MMCCs	134
4.5.1	Fault-tolerant operation	134
4.5.2	Floating DC capacitor pre-charging procedures	136
4.6	Main applications	136
	Acknowledgements	138
	References	138

5 Matrix converters	147
5.1 Introduction	147
5.2 Direct matrix converter	147
5.2.1 Circuit topology	147
5.2.2 Modulation techniques	147
5.3 Indirect matrix converter	159
5.3.1 Circuit topology	161
5.3.2 Modulation techniques	162
5.4 Technological issues of MCs	165
5.5 MC versus voltage back-to-back converter	167
5.6 Summary	167
References	168
6 Soft-switching converters	169
6.1 Resonant converters	169
6.1.1 Second-order resonant converters	169
6.1.2 Resonant converters with three or more resonating elements	178
6.2 Quasi-resonant converters	181
6.2.1 Example 1 – half-wave ZCS-QRC	183
6.2.2 Example 2 – full-wave ZCS-QRC	185
6.2.3 Example 3 – half-wave ZVS-QRC	186
6.2.4 Example 4 – full-wave ZVS-QRC	188
6.2.5 The effect of parasitic oscillations in QRCs	189
6.3 Multi-resonant converters	190
6.4 Quasi-square-wave converters	191
6.5 Other types of ZVS and ZCS converters	196
References	200
7 Z-source converters	205
7.1 Introduction	205
7.1.1 General overview	205
7.1.2 Basic principles	207
7.1.3 Modeling and control	209
7.2 Categories of impedance source power converters based on conversion functionality	215
7.2.1 DC–DC converter topologies	215
7.2.2 DC–AC inverter topologies	222
7.2.3 AC–AC converter topologies	226
7.2.4 AC–DC converter topologies	227
7.3 Impedance source network topologies	227
7.3.1 Non-transformer based	229
7.3.2 With transformer or magnetic coupling	233
7.4 Conclusions	236
References	237

8 Switching power supplies	245
8.1 Introduction	245
8.2 Non-isolated converters topologies	246
8.2.1 Buck converter	246
8.2.2 Boost converter	249
8.2.3 Buck-boost converter	251
8.2.4 Integrated buck and boost converter	252
8.2.5 Power factor correction	253
8.3 Isolated converters topologies	254
8.3.1 Flyback converter	254
8.3.2 Forward converter	255
8.3.3 Half-bridge converter	256
8.3.4 Full-bridge converter	258
8.3.5 Rectifiers	259
8.4 Parasitics in DC-DC converters	262
8.5 Continuous and discontinuous conduction modes	264
8.6 Synchronous rectification	264
8.7 Bidirectional converters	265
8.8 Interleaving	266
8.9 Control principles	268
Further reading	272
9 Smart power electronic modules	273
9.1 History	273
9.2 Technology background	276
9.2.1 IGBT device technologies and their performance	277
9.2.2 Gate driver technology	280
9.2.3 Packaging technologies	282
9.3 Basic usage	284
9.3.1 Protection	284
9.3.2 Bootstrap power supply	285
9.3.3 Digital interface	287
9.4 Reliability	287
9.5 Variety of products	288
9.6 Future usage and emerging solutions	290
9.6.1 Grid interface with multiple power modules	290
9.6.2 Matrix converter with SPM devices	295
9.6.3 Multilevel converter with SPM devices	296
9.6.4 A different direct converter with SPM devices	298
9.7 Conclusion	306
References	306
Part II Applications	311
10 Permanent magnet synchronous motor drives	313
10.1 Introduction	313
10.2 Trends in sensorless control of PMSM	314

10.2.1	Key factors for sensorless controls evaluation	315
10.2.2	A glance to HF injection methods	316
10.2.3	A HF sensorless technique for IPM and PMASR motors	318
10.2.4	A HF injection method for surface-mounted permanent magnet motors	319
10.2.5	A glance to extended EMF-based methods	320
10.2.6	Sliding mode observers for the extended EMF	321
10.3	Trends in MPC of PMSM	322
10.3.1	Key factors for MPC	323
10.3.2	Direct torque and flux control	323
10.3.3	An MPC method for IPM motors	324
10.3.4	A perspective on centralised MPC-based structures	325
10.4	Some hints about energy efficiency in PMSM drives	326
10.5	Final considerations	327
	Acknowledgements	328
	References	328
11	Induction motor drives	333
11.1	Induction motors	333
11.2	IM model	334
11.3	Variable frequency drives	335
11.3.1	Scalar control	335
11.3.2	Field-oriented control	335
11.3.3	Direct torque control	336
11.4	DTC schemes	336
11.4.1	Space vector modulation DTC	336
11.4.2	Feedback linearization and sliding mode DTC	337
11.4.3	Intelligent DTC schemes	340
11.5	IM speed estimation with Kalman filtering	342
11.5.1	High-speed operation	343
11.5.2	Low-speed operation	344
11.5.3	Implementation considerations	346
11.6	Switched reluctance sensorless drives	348
	References	349
12	Wind energy systems	351
12.1	Introduction	351
12.1.1	Overview of the wind energy technology	351
12.1.2	Types of WT rotors	352
12.1.3	Generators for WTs and standard configurations of WECSs	354
12.2	Power electronic interfaces for variable speed WTs	361
12.2.1	Conventional power electronic building blocks	363
12.2.2	Common PEC topologies for WTs	366
12.2.3	Emerging PEC topologies for WTs	369
12.2.4	PEC topologies for high power WTs	371

12.3	Control algorithms for PECs	374
12.3.1	Maximum power point tracking	375
12.3.2	Control for DC/DC boost converters	377
12.3.3	Control for IS converters	378
12.3.4	Field oriented control	380
12.3.5	Direct torque control-space vector modulated	382
12.3.6	Voltage oriented control	382
12.3.7	Direct power control-space vector modulated	384
12.3.8	Single-phase grid converter control	385
12.3.9	Control for stand-alone mode of operation	386
	Acknowledgements	388
	References	388
13	Photovoltaic energy systems	395
13.1	Introduction	395
13.1.1	Brief overview of photovoltaic generation	395
13.1.2	PV inverter circuit	395
13.1.3	Centralized PV plant	397
13.2	The technologies	399
13.2.1	State-of-the-art technologies	399
13.2.2	Reliability	404
13.3	The grid interface	409
13.3.1	Basic control of real and reactive power in a two-bus power system	409
13.4	The standards	414
13.4.1	Protection	417
13.4.2	Islanding	417
13.4.3	Power quality	419
13.4.4	Ancillary services	420
13.5	The field measurements	422
13.5.1	Intermittence in solar field results	422
13.5.2	LVRT test results of the 500 kW RX series	422
13.6	Summary and conclusions	423
	Acknowledgements	424
	References	424
14	Automotive energy systems	425
14.1	Electric vehicle batteries	425
14.1.1	Introduction	425
14.2	EV charging	440
14.2.1	Plugged charging	440
14.3	Wireless charging	456
14.3.1	Introduction	456
14.3.2	Necessity of compensation for wireless charging	458
14.3.3	Analysis of series-series topology	461
14.3.4	Analysis of series-parallel topology	461

14.3.5	Peak efficiency of series-series and series-parallel topology	462
14.3.6	Control strategies for SS and SP topology	463
14.3.7	Advantages of EV wireless charging	464
	References	464
15	Shipboard power systems	469
15.1	Shipboard power system topologies	469
15.2	Shipboard propulsion drives	472
15.2.1	Voltage link systems	474
15.2.2	Current link systems	477
15.2.3	Direct AC-AC conversion – cycloconverters	478
15.3	Power quality requirements in shipboard systems	479
15.4	Harmonic mitigation in shipboard systems	483
15.4.1	Harmonic cancellation	483
15.4.2	Reactive harmonic suppressors	485
15.4.3	Active filters	489
15.4.4	Case study	492
15.5	Frequency variation and converter control	495
15.6	Concepts for future shipboard power systems	495
15.6.1	Power electronics building block	495
15.6.2	Medium voltage DC integrated power system	496
	Acknowledgements	498
	References	498
16	Converters in power grid	501
16.1	Introduction	501
16.2	Power converter topologies	501
16.2.1	AC-DC converters	502
16.2.2	AC phase controllers	505
16.2.3	AC pulse width modulated controllers	505
16.2.4	Modular multilevel converter	508
16.3	Application examples of power converters in power grid	512
16.3.1	Shunt compensation	512
16.3.2	Series compensation	515
16.3.3	Shunt-series compensation	521
16.3.4	Series-series compensation	523
16.3.5	High-voltage direct current transmission	524
16.3.6	Low-frequency high-voltage ac transmission	526
16.3.7	Solid-state power transformer	528
16.4	Summary	529
	References	530
17	Distributed generation and microgrids	535
17.1	Introduction	535
17.2	Distribution generators	536

17.2.1	Examples of DGs	536
17.2.2	Technical impacts due to DG	541
17.2.3	IEEE1547	544
17.3	Microgrid	545
17.3.1	DC and AC microgrids	546
17.3.2	Stand-alone microgrids	546
17.3.3	Grid-tied microgrids	546
17.3.4	Centralized control	547
17.3.5	Conventional droop control method	547
17.3.6	Local control	550
17.3.7	Multifunctionalities	551
	References	553
18	Uninterruptible power supplies	557
18.1	Introduction	557
18.2	Topologies	557
18.2.1	On-line UPS systems	557
18.2.2	Off-Line UPS	558
18.2.3	Line-interactive UPS	560
18.2.4	Delta conversion UPS	561
18.2.5	Tri-mode UPS	561
18.2.6	Rotary UPS	562
18.2.7	Hybrid static and rotary UPS	563
18.2.8	Flywheels	564
18.2.9	DC UPS for pulse load with power leveling	565
18.2.10	Redundant bus	566
18.3	Controls for UPS systems	566
18.4	Applications	571
18.4.1	Desktop personal computers	572
18.4.2	Industrial systems	572
18.4.3	Data centers	572
18.4.4	Medical equipment	572
	References	573
19	Wireless power transfer	577
19.1	Introduction	577
19.2	Basic principles and two fundamental concepts of WPT	579
19.2.1	Basic principles	579
19.2.2	Two fundamental concepts	580
19.3	Different forms of WPT systems	582
19.3.1	Two-coil systems	582
19.3.2	Three-coil systems	583
19.3.3	Four-coil systems	584
19.3.4	WPT systems with relay and domino resonators	585

19.4	Power electronics and control	585
19.4.1	Series and parallel tuned primary and secondary circuits	586
19.4.2	Practical circuit topologies	588
19.4.3	Control	592
19.5	Safety regulations	594
19.5.1	Electromagnetic compatibility	594
19.5.2	Human exposure	595
19.6	Conclusion	597
	Acknowledgements	597
	References	597
20	Advanced control of power electronic systems	601
20.1	Introduction	601
20.2	Brief overview of historic advanced nonlinear controllers for PES applications	601
20.3	Switching SBC [9–11]	604
20.3.1	SBC for standalone PES	604
20.3.2	SBC for networked PESs	610
	Acknowledgements	617
	References	617
Index		619