Contents

Authors' biographies ix
Preface xi
List of symbols xiii

1 Introduction 1
1.1 Introduction 1
1.2 Voltage regulator applications 3
1.3 Voltage source gate driver and high-frequency-dependent loss 4
1.3.1 Switching loss 5
1.3.2 Body diode conduction loss 9
1.3.3 Reverse recovery loss 10
1.3.4 Gate drive loss 10
1.4 Summary 10
References 11

2 Fundamentals of current source driver 13
2.1 Resonant gate drivers 13
2.2 Concept of current source driver 17
2.3 A practical and accurate switching loss model 19
2.3.1 Introduction 19
2.3.2 Impact of parasitic inductance and load current 20
2.3.3 Proposed switching loss model 24
2.3.4 Turn-on switching loss model 25
2.3.5 Turn-off switching loss model 32
2.3.6 Voltage source drive model verification 37
2.3.7 Experimental validation of the voltage source drive model 38
2.4 Summary 42
References 42

3 Continuous current source driver 45
3.1 Two-channel low-side continuous current source drivers 45
3.1.1 Operating principle 45
3.1.2 Loss comparison 49
3.1.3 Advantages of the proposed current source driver 52
3.1.4 Applications 54
3.1.5 Experimental results 56

3.2 High-side and low-side continuous current source drivers 59
3.2.1 Operating principle of proposed current source drivers 59
3.2.2 Advantages 63
3.2.3 Loss analysis 65
3.2.4 Experimental results 67
3.3 Accurate switching loss model with current source drivers 69
3.3.1 Proposed MOSFET loss model with current source resonant driver 69
3.3.2 Analytical modeling and simulation results 73
3.3.3 Proposed optimal design with the accurate switching loss model 75
3.3.4 Experimental verification and discussion 79
3.4 High-side and low-side current source drivers 86
3.4.1 Problem of high-side and low-side current source drivers 86
3.4.2 Proposed decoupled high-side and low-side current source drivers 87
3.4.3 New current-source gate driver with integrated magnetics 94
3.4.4 Experimental results and discussion 96
3.5 Summary 101
References 101

4 Discontinuous current source drivers 103
4.1 Discontinuous current source driver 103
4.1.1 Proposed low-side discontinuous CSD 103
4.1.2 Driver loss analysis 107
4.1.3 CSD design procedure 115
4.1.4 Design example 116
4.1.5 Experimental results 117
4.2 High-side discontinuous CSD 123
4.2.1 Proposed CSD for synchronous buck converter and operation 123
4.2.2 Design example 125
4.2.3 Experimental results 125
4.3 Discontinuous CSD with reduced inductance 132
4.3.1 Proposed CSD and principle of operation 132
4.3.2 Proposed high-side CSD and hybrid gate-drive scheme 137
4.3.3 Experimental results 139
4.4 Current diversion 145
4.4.1 Introduction 145
4.4.2 Proposed switching loss model considering current diversion 147
4.4.3 Experimental results and discussions 154
4.5 Summary 157
References 158

5 Adaptive current source drivers **159**
5.1 Adaptive current source driver for buck converters 159
5.1.1 Introduction 159
5.1.2 Adaptive continuous current source driver 159
5.1.3 Adaptive discontinuous current source drivers 161
5.1.4 Implementation of the adaptive drive voltage for the current source drivers 163
5.1.5 Experimental results and discussion 164
5.2 Adaptive current source driver for power factor correction application 166
5.2.1 Introduction 166
5.2.2 Analysis of current source driver circuits and proposed adaptive current source driver for boost power factor correction converters 166
5.2.3 Loss analysis of proposed adaptive current source driver for boost power factor correction converter 168
5.2.4 Experimental results and discussion 172
5.3 Digital adaptive power factor correction 173
5.3.1 Introduction 173
5.3.2 Principle of the proposed digital adaptive discontinuous current source driver 175
5.3.3 Design procedure and implementation 176
5.3.4 Experimental results and discussion 182
5.4 Summary 186
References 187

6 Resonant gate drivers **189**
6.1 Resonant gate drivers for multi-megahertz isolated resonant converters 189
6.1.1 Introduction 189
6.1.2 Challenges for the SR drive in the multi-MHz isolated resonant converters 190
6.1.3 Proposed self-driven RGD for the SR 192
6.1.4 Experimental verification and discussion 202
6.2 A high-frequency dual-channel isolated resonant gate driver with low gate-drive loss for ZVS full-bridge converters 206
6.2.1 Introduction 206
6.2.2 Review of gate-drive circuits 207
6.2.3 Proposed resonant gate driver for FB converters and principle of operation 208
6.2.4 Loss analysis and optimal design 211
6.2.5 The comparison between the proposed RGD and previous gate-drive circuits 220
6.2.6 Experimental results and discussion 224
6.3 Summary 226
References 227

7 eGaN HEMTs gate drivers **231**
7.1 Three-level gate drivers 231
7.1.1 Introduction 231
7.1.2 Driving requirements for eGaN HEMTs in resonant SEPIC converters 232
7.1.3 Proposed three-level gate drivers for eGaN HEMTs 235
7.1.4 Operation principle of three-level gate driver 237
7.1.5 Rectifier mathematic modeling and design 241
7.1.6 Experimental results and discussion 248
7.2 A digital adaptive driving scheme for eGaN HEMTs in VHF converters 252
7.2.1 Introduction 252
7.2.2 Gate-drive challenges for eGaN VHF converters 254
7.2.3 Proposed digital adaptive driving scheme 256
7.2.4 Relationship analysis between gate-drive timing and input voltage 258
7.2.5 Air-core transformer design 263
7.2.6 Experimental results and discussion 264
7.3 Summary 270
References 270

Index **273**